

Autonomous Instruments and Feature Extractor Feedback Systems

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15 june 2012

Autonomous instruments

- ▶ Generate music by algorithms from the waveform to an entire composition
- ▶ No realtime interaction
- ▶ Essentially a deterministic autonomous system

Bytebeat

One-liners:

```
int t;  
for(t=0; t<T; t++)  
    putchar( expression );
```

Sawtooth wave:

$3.5*t$

Periodic pattern:

$5*t \wedge 3*(t + t\%12) | (t/125)$

Analog feedback systems as autonomous instruments



Patch **without feedback**

Same **with feedback**

Dynamic systems

Consider a map $f : \mathbb{R}^d \rightarrow \mathbb{R}^d$.

Generate a time series \mathbf{x}_n by iteration:

$$\mathbf{x}_{n+1} = f(\mathbf{x}_n) \quad \text{or} \quad \mathbf{x}_n = f^n(\mathbf{x}_0)$$

Use \mathbf{x}_n as audio samples.

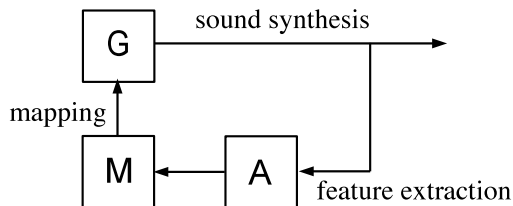
Qualitative dynamics:

- ▶ Fixed point: $\mathbf{x}_{n+1} = \mathbf{x}_n$
- ▶ Periodic: $\mathbf{x}_{n+T} = \mathbf{x}_n$
- ▶ Quasi-periodic
- ▶ Unbounded: $\lim_{n \rightarrow \infty} \|\mathbf{x}_n\| = \infty$
- ▶ Chaotic

Feature extractor feedback systems (FEFS)

Basic ingredients:

- ▶ Oscillator (signal generator) **G**
- ▶ Feature extractor / analysis **A**
- ▶ Mapping **M**



The FEFS equation

$$\begin{aligned}x_n &= \mathbf{G}(\pi_n, n) \\ \phi_n &= \mathbf{A}(x_n, x_{n-1}, \dots, x_{n-L+1}) \\ \pi_{n+1} &= \mathbf{M}(\phi_n, \pi_n)\end{aligned}$$

where

π are the synthesis parameters

ϕ is the feature extractor signal

Feature extraction

Low level feature extractors:

- ▶ RMS amplitude

$$RMS(x_n) = \langle x_n^2 \rangle^{1/2}$$

- ▶ Spectral centroid

$$Centroid(x_n) = \frac{RMS(\frac{d}{dn}(x_n))}{RMS(x_n)}$$

The extended time window

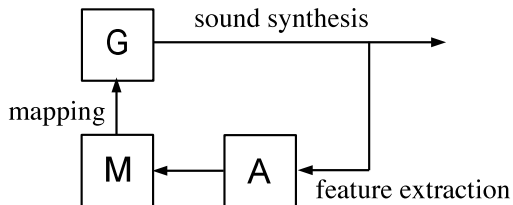
$$\phi_n = \mathbf{A}(x_n, x_{n-1}, \dots, x_{n-L+1})$$

causes smoothing of x_n .

Simplified structure of the FEFS equation:

$$x_n = \mathbf{F}(x_{n-1}, x_{n-2}, \dots, x_{n-L})$$

FEFS example



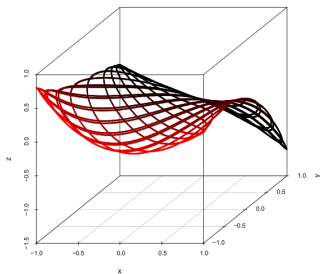
G: Wave terrain synthesis

A: amplitude + centroid

M: complicated mapping

Wave terrain synthesis

$$\begin{aligned}z_n &= f_\mu(x_n, y_n) \\x_n &= A_x \cos(\omega_x n) \\y_n &= A_y \cos(\omega_y n)\end{aligned}$$



where $f_\mu(x, y) = \mu_1 x_n y_n + \mu_2 (x_n^2 - y_n^2) + \mu_3 (x_n + y_n)^3$

Seven free parameters: $\pi = (A_x, A_y, \omega_x, \omega_y, \mu_1, \mu_2, \mu_3)$

The wave terrain system

Send $z_n = f_\mu(x_n, y_n)$ to feature extractors

$$\phi_1(z_n) \equiv \text{RMS}(z_n)$$

$$\phi_2(z_n) \equiv \text{Centroid}(z_n)$$

Map the features to synthesis parameters with $\mathbf{M} : \mathbb{R}^2 \rightarrow \mathbb{R}^7$,

$$\pi_{n+1} = f(\phi_1(z_n), \phi_2(z_n))$$

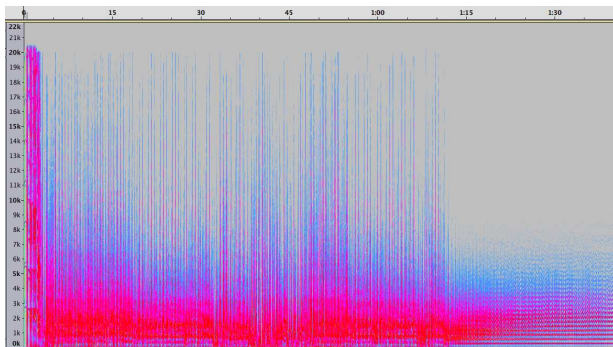
The mapping

```
242 void mapp::map(double AA, double CC, params &pp)
243 {
244 // amp AA, centroid CC --> params. pp; internal coefs
245
246 pp.a = a[0] + a[1]*CC + a[2]*AA + a[3]*CC*CC + a[4]*AA*AA + a[5]*CC*AA;
247 pp.b = b[0] + b[1]*CC + b[2]*AA + b[3]*CC*CC + b[4]*AA*AA + b[5]*CC*AA;
248 pp.c = c[0] + c[1]*CC + c[2]*AA + c[3]*CC*CC + c[4]*AA*AA + c[5]*CC*AA;
249
250 pp.A = A[0] + A[1]*CC + A[2]*AA + A[3]*cos(A[5]*CC + A[6]) + A[4]*cos(A[7]*AA + A[8]);
251 pp.B = B[0] + B[1]*CC + B[2]*AA + B[3]*cos(B[5]*CC + B[6]) + B[4]*cos(B[7]*AA + B[8]);
252
253 pp.f1 = F[0] + F[1]*CC + F[2]*AA + F[3]*cos(F[5]*CC + F[6]) + F[4]*cos(F[7]*AA + F[8]);
254 pp.f2 = G[0] + G[1]*CC + G[2]*AA + G[3]*cos(G[5]*CC + G[6]) + G[4]*cos(G[7]*AA + G[8]);
255
256 }
257
```

54 new constants for the mapping!

The halting problem

Very long **chaotic transients**
or **stable chaos** that goes on forever?

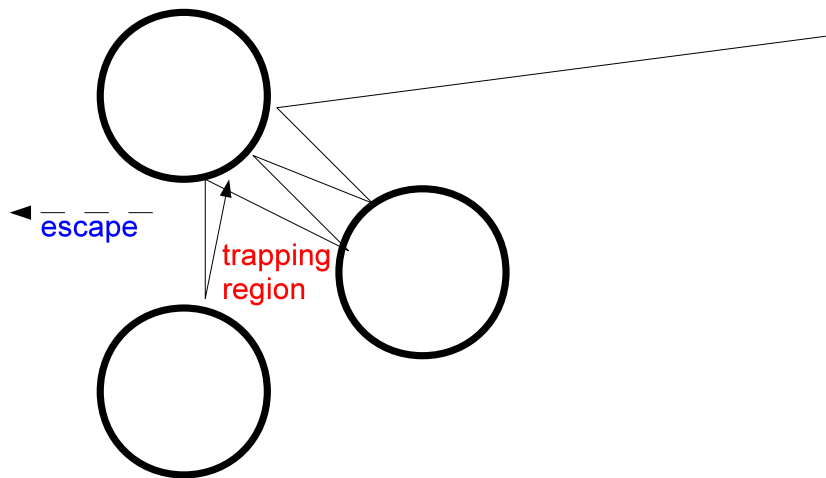


Repetition detector

$$\begin{aligned} & \text{if}(|a_n - a_{n-d}| < \epsilon \\ & \& |a_{n-d} - a_{n-2d}| < \epsilon \\ & \& |c_n - c_{n-d}| < \epsilon \\ & \& |c_{n-d} - c_{n-2d}| < \epsilon) \end{aligned}$$

then halt!

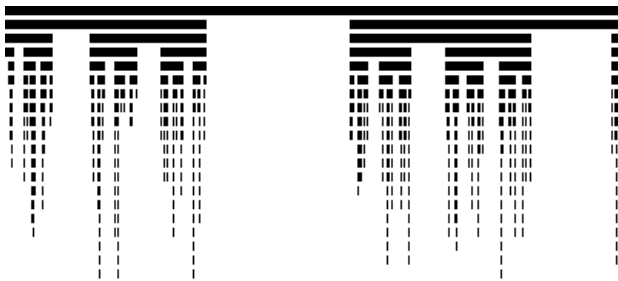
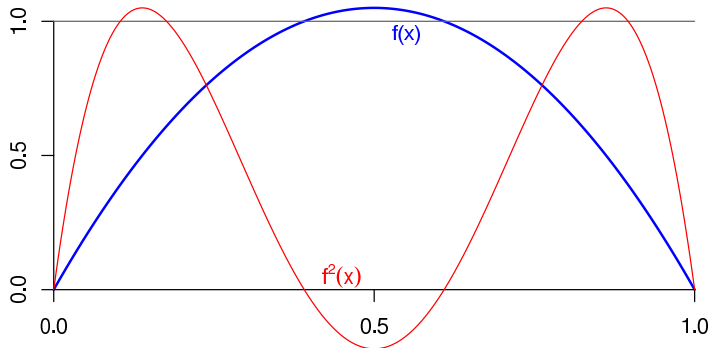
Chaotic scattering



Chaotic transients (pinball game)

Cantor sets

Logistic map



Halting times

